

# Ultrasonic sensor

## UB500-F42-E4-V15

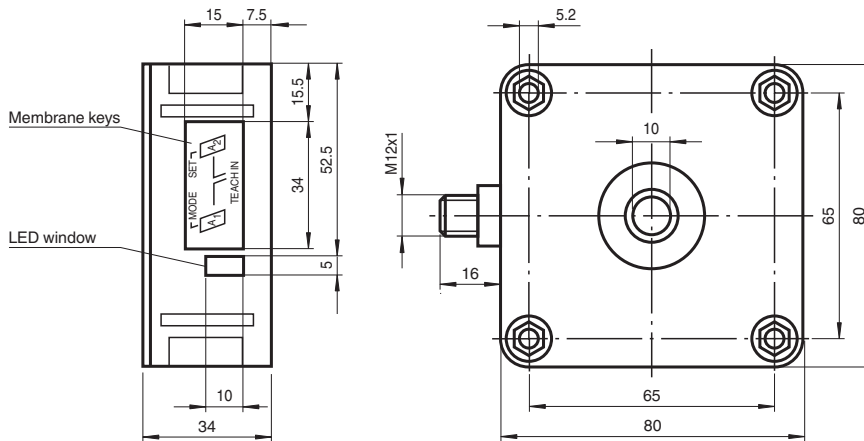


- Switching output
- Extremely small unusable area
- TEACH-IN
- Interference suppression (adjustable divergence of sound cone in close range)
- Temperature compensation
- Synchronization options
- NO/NC selectable

Single head system



### Dimensions



### Technical Data

General specifications		
Sensing range		30 ... 500 mm
Adjustment range		50 ... 500 mm
Dead band		0 ... 30 mm
Standard target plate		100 mm x 100 mm
Transducer frequency		approx. 390 kHz
Response delay		approx. 50 ms
Indicators/operating means		
LED green		solid green: Power on
LED yellow		solid: switching state switch output flashing: program function
LED red		normal operation: "fault" program function: no object detected
Electrical specifications		
Operating voltage	$U_B$	10 ... 30 V DC , ripple 10 % <sub>SS</sub>
No-load supply current	$I_0$	≤ 50 mA
Input/Output		

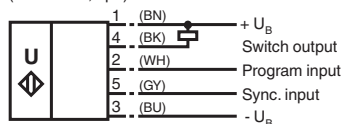
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## Technical Data

Synchronization		bi-directional 0 level $-U_B \dots +1 \text{ V}$ 1 level: $+4 \text{ V} \dots +U_B$ input impedance: $> 12 \text{ KOhm}$ synchronization pulse: $\geq 100 \mu\text{s}$ , synchronization interpulse period: $\geq 2 \text{ ms}$
Synchronization frequency		
Common mode operation		max. 95 Hz
Multiplex operation		$\leq 95/n \text{ Hz}$ , n = number of sensors
<b>Output</b>		
Output type		1 switching output E4, NPN, NO/NC, programmable
Rated operating current	$I_e$	200 mA, short-circuit/overload protected
Default setting		Switch point A1: 50 mm, Switch point A2: 500 mm, wide sound lobe
Voltage drop	$U_d$	$\leq 2.5 \text{ V}$
Repeat accuracy		$\leq 0.5 \%$ of switching point
Switching frequency	f	$\leq 8 \text{ Hz}$
Range hysteresis	H	1 % of the set operating distance
Temperature influence		$\pm 1 \%$ of full-scale value
<b>Compliance with standards and directives</b>		
Standard conformity		
Standards		EN IEC 60947-5-2:2020 IEC 60947-5-2:2019
<b>Approvals and certificates</b>		
UL approval		cULus Listed, Class 2 Power Source
CCC approval		CCC approval / marking not required for products rated $\leq 36 \text{ V}$
<b>Ambient conditions</b>		
Ambient temperature		$-25 \dots 70 \text{ }^\circ\text{C}$ ( $-13 \dots 158 \text{ }^\circ\text{F}$ )
Storage temperature		$-40 \dots 85 \text{ }^\circ\text{C}$ ( $-40 \dots 185 \text{ }^\circ\text{F}$ )
<b>Mechanical specifications</b>		
Connection type		Connector plug M12 x 1, 5-pin
Degree of protection		IP54
Material		
Housing		ABS
Transducer		epoxy resin/hollow glass sphere mixture; foam polyurethane, cover PBT
Mass		140 g
Dimensions		
Height		80 mm
Width		80 mm
Length		34 mm

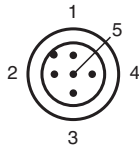
## Connection Assignment

Standard symbol/Connections:  
(version E4, npn)



Wire colors in accordance with EN 60947-5-2.

## Connection Assignment

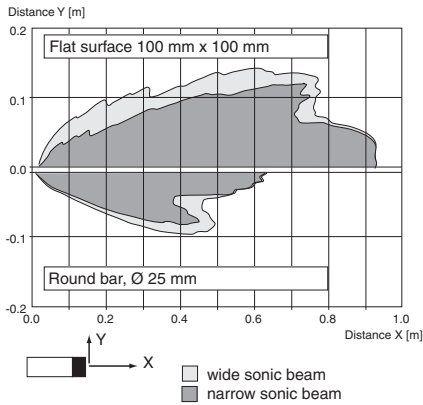


Wire colors in accordance with EN 60947-5-2

1	BN	(brown)
2	WH	(white)
3	BU	(blue)
4	BK	(black)
5	GY	(gray)

## Characteristic Curve

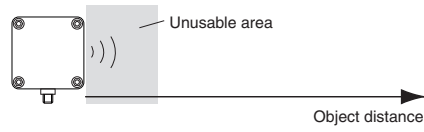
### Characteristic response curve



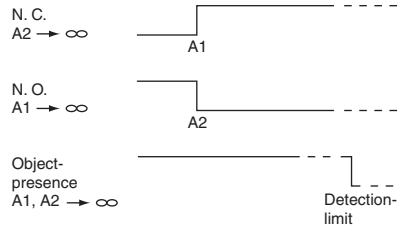
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**Characteristic Curve**

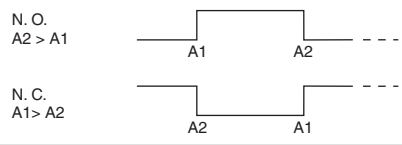
**Programmable operation modes**



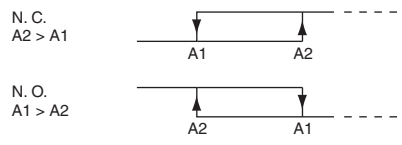
**1. Switching point mode**



**2. Window mode**



**3. Hysteresis mode**



**Note:**  
 → ∞ means: cover transducer surface with your hand, while teaching the switching point.  
 If A1 = A2, the output works like A2 > A1

**Programming**

**Functional Description**

The sensor may be completely parameterised via two keys on the side panel of the housing. As a special feature provided by this sensor, the ultrasound beam width may be adapted to the environmental conditions at the place of operation of the sensor.

**Specifying the switching points:**

When specifying the switching points, the user determines at which points the switching output changes its state. The order of the switching points  $A1 > A2$ , or  $A1 < A2$  also determines the direction of action (i.e. normally-closed/normally-open contact function).

Specifying the A1 switching point by pressing the A1 key	
Holding down the A1 key > 2 seconds	The sensor switches to learn mode and the user may specify the A1 switching point
Positioning the target object at the desired distance	The yellow LED of the sensor flashes fast to indicate that the target object has been recognised. The red LED flashes if the object has not been recognised.
Briefly pressing the A1 key	The sensor terminates the specification of the A1 switching point and saves it as a non-volatile value. The specified value is invalid if the object is uncertain (i.e. the red LED lights up at irregular intervals). The learn mode is exited.

**The A2 switching point is specified via the A2 key, analogous to the description above.**

Alternatively, the switching points may also be specified electrically via the learn input. To specify the A1 switching point, the learn input must be connected to

$-U_B$ ; to specify the A2 switching point, it must be connected to  $+U_B$ . Specified values are saved upon the disconnection from the learn input.

Switching points may only be specified directly after Power on. A time lock secures the adjusted switching points against unintended modification 5 minutes after the last keypress. To modify the switching points later, the user may specify the desired values only after a new Power On.

**Proceed as follows to parameterise the output function and the ultrasound beam width:**

Press the A1 key during Power on and hold down the key for another second to ensure that the sensor starts the two-step parameterisation of the operating modes.

**Step 1, parameterisation of the output function**

The output function parameterised last is displayed. All output functions available may be selected via consecutive, brief strokes of the A2 key. These strokes are visualised via short flashes of the green LED.

Operating mode	Flash sequence of the green LED	A2 key
1 switching point/ object detection		
Window function (default)		
Hysteresis mode		

Hold down the A1 key for 2 seconds to save the selected output mode, complete the parameterisation and ensure that the sensor returns to normal mode. Step 2 may be initiated by briefly pressing the A1 key (parameterisation of the ultrasound beam width).

**Step 2, parameterisation of the ultrasound beam width**

In the near range, via Step 2, the ultrasound beam width may be adapted to the requirements of the corresponding application. The beam width parameterised last is displayed first. Available beam width settings may be selected via consecutive, brief strokes of the A2 key. These strokes are visualised via the flash sequence of the red LED.

Beam width	Flash sequence of the red LED	A2 key
Small beam		
Medium beam		
Large beam		

Hold down the A1 key for 2 seconds to save the selected beam shape, complete the parameterisation and ensure that the sensor returns to normal mode. Briefly press the A1 key to return to Step 1 (parameterisation of the output function).

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If the parameterisation mode is not terminated within 5 minutes after last keypress (by holding down the A1 key for 2 seconds), the sensor aborts this mode without modifying the settings.

### Synchronisation

The sensor has a synchronisation port to suppress mutual influencing. If this port has not been connected, the sensor works at an internally generated cycle rate. Several sensors may be synchronised via the following options.

External synchronisation:

The sensor may be synchronised via the external application of a square wave voltage. A synchronisation pulse on the synchronisation input initiates a measuring cycle. The pulse width must be greater than 100 µs. The measuring cycle is started with the falling edge. A low level > 1 s or an open synchronisation input initiate the transition to normal sensor mode. A high level on the synchronisation input deactivates the sensor.

Two modes are possible:

- Several sensors are controlled via the same synchronisation signal. The sensors work in common mode.
- The synchronisation pulses are forwarded at cyclic intervals to respectively one single sensor. The sensors work in multiplex mode.

Self-synchronisation:

The synchronisation ports of up to 5 sensors suitable for self-synchronisation are connected to each other. These sensors work in multiplex mode after Power on. The On delay increases depending on the number of sensors to be synchronised. While the learn mode is active, no synchronisation is possible (and vice-versa). To specify the switching points, the sensors must be operated in non-synchronised mode.

### Note:

If the synchronisation option is not used, the synchronisation input must be connected to ground (0V) or the sensor must be operated with a (4-pole) V1 connecting cable.

## Accessories

### Mounting aids

MH 04-3505

MHW 11

### Cable sockets \*)

V15-G-2M-PVC

V15-W-2M-PUR

\*) For additional cable sockets see section „Accessories“.