



Ultrasonic sensor

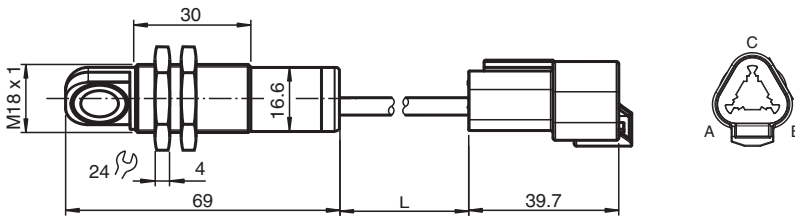
UB800-18GM40A-I-0,3M-Y70110930

- Cylindrical housing
- Analog output 4 mA ... 20 mA
- Temperature compensation
- Deutsch connector 3-pin

Single head system



Dimensions



Technical Data

General specifications

| | |
|-----------------------|-----------------|
| Sensing range | 50 ... 800 mm |
| Adjustment range | 70 ... 800 mm |
| Dead band | 0 ... 50 mm |
| Standard target plate | 100 mm x 100 mm |
| Transducer frequency | approx. 255 kHz |
| Response delay | approx. 100 ms |

Indicators/operating means

| | |
|------------|----------------------------|
| LED green | Power on |
| LED yellow | object in evaluation range |
| LED red | error |

Electrical specifications

| | | |
|------------------------|-------|--|
| Operating voltage | U_B | 10 ... 30 V DC , ripple 10 % _{SS} |
| No-load supply current | I_0 | ≤ 20 mA |

Output

| | |
|---------------------------------------|---|
| Output type | 1 analog output 4 ... 20 mA, short-circuit/overload protected |
| Default setting | evaluation limit A1: 70 mm evaluation limit A2: 800 mm |
| Resolution | 0.4 mm at max. sensing range |
| Deviation of the characteristic curve | ± 1 % of full-scale value |
| Repeat accuracy | ± 0.5 % of full-scale value |
| Load impedance | 0 ... 300 Ω at $U_B > 10$ V; 0 ... 500 Ω at $U_B > 15$ V |
| Temperature influence | ± 1.5 % of full-scale value |

Compliance with standards and directives

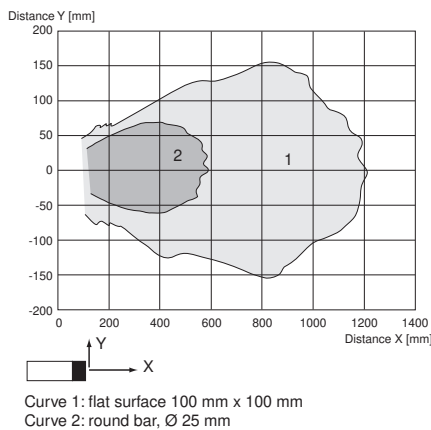
Release date: 2025-05-16 Date of issue: 2025-05-16 Filename: 70110930_eng.pdf

Technical Data

| | |
|-----------------------------------|--|
| Standard conformity | |
| Standards | EN IEC 60947-5-2:2020 IEC 60947-5-2:2019 EN 60947-5-7:2003 IEC 60947-5-7:2003 |
| Approvals and certificates | |
| UL approval | cULus Listed, Class 2 Power Source |
| CCC approval | CCC approval / marking not required for products rated ≤36 V |
| Ambient conditions | |
| Ambient temperature | -25 ... 70 °C (-13 ... 158 °F) |
| Storage temperature | -40 ... 85 °C (-40 ... 185 °F) |
| Mechanical specifications | |
| Connection type | fixed cable with plug |
| Degree of protection | IP67 |
| Material | |
| Housing | brass, nickel-plated |
| Transducer | epoxy resin/hollow glass sphere mixture; foam polyurethane, cover PBT |
| Connector | Deutsch connector DT04-3P-C015 |
| Cable | |
| Material | PVC |
| Length | L 300 mm |
| Mass | 55 g |
| Dimensions | |
| Length | 72.6 mm |
| Diameter | 18 mm |

Characteristic Curve

Characteristic response curve



Release date: 2025-05-16 Date of issue: 2025-05-16 Filename: 70110930_eng.pdf

Programming

Programming procedure

The sensor features a programmable analog output with two programmable evaluation boundaries. Programming the evaluation boundaries and the operating mode is done by applying the supply voltage $-U_B$ or $+U_B$ to the Teach-In input. The supply voltage must be applied to the Teach-In input for at least 1 s. LEDs indicate whether the sensor has recognized the target during the programming procedure.

Note:

Evaluation boundaries may only be specified directly after Power on. A time lock secures the adjusted switching points against unintended modification 5 minutes after Power on. To modify the evaluation boundaries later, the user may specify the desired values only after a new Power On.

Note:

If a programming adapter UB-PROG2 is used for the programming procedure, button A1 is assigned to $-U_B$ and button A2 is assigned to $+U_B$.

Programming the analog output

Rising ramp

1. Place the target at the near end of the desired evaluation range
2. Program the evaluation boundary by applying $-U_B$ to the Teach-In input (yellow LED flashes)
3. Disconnect the Teach-In input from $-U_B$ to save the evaluation boundary
4. Place the target at the far end of the desired evaluation range
5. Program the evaluation boundary by applying $+U_B$ to the Teach-In input (yellow LED flashes)
6. Disconnect the Teach-In input from $+U_B$ to save the evaluation boundary

Falling ramp

1. Place the target at the far end of the desired evaluation range
2. Program the evaluation boundary by applying $-U_B$ to the Teach-In input (yellow LED flashes)
3. Disconnect the Teach-In input from $-U_B$ to save the evaluation boundary
4. Place the target at the near end of the desired evaluation range
5. Program the evaluation boundary by applying $+U_B$ to the Teach-In input (yellow LED flashes)
6. Disconnect the Teach-In input from $+U_B$ to save the evaluation boundary