



# Multitrurn absolute rotary encoder ESM78E-E

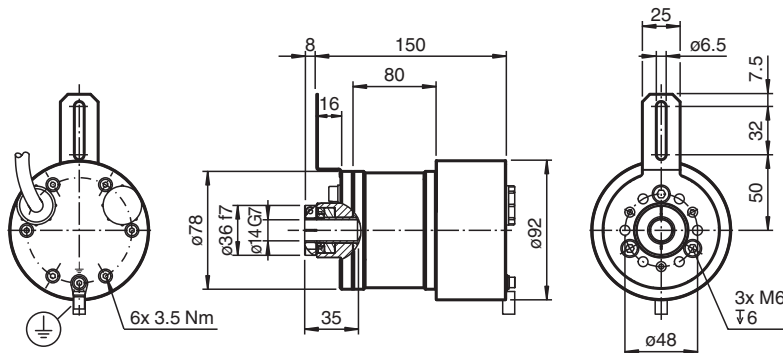
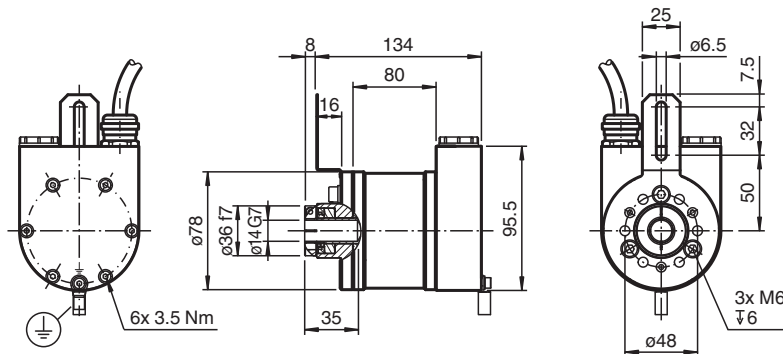
- Up to 30 Bit multitrurn
- ATEX approval
- IECEx approval
- Flameproof enclosure
- Removable connection cap



## Function

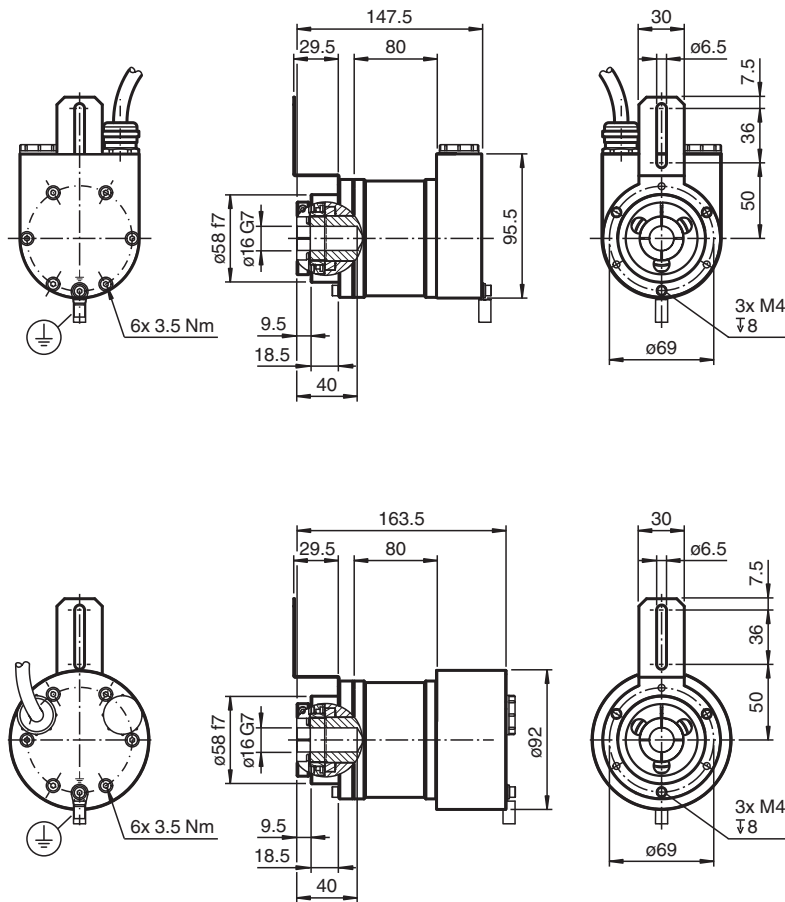
Absolute multitrurn rotary encoders deliver an absolute step value for each angle setting. This device has a maximum basic resolution of 65536 steps per revolution (16 bits) and codes up to 16384 revolutions (14 bits). Thus the overall resolution amounts to 30 bits. On account of the high number of measuring steps resulting (more than 1 billion), this type of encoder can be used to divide very long linear distances into small measuring steps. The device is designed for mounting on shaft diameter 14 mm or 16 mm.

## Dimensions



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## Dimensions



## Technical Data

General specifications	
Detection type	photoelectric sampling
Device type	Multiturn absolute rotary encoder
Functional safety related parameters	
MTTF <sub>d</sub>	25 a
L <sub>10</sub>	7.7 E+9 at 3000 rpm
Electrical specifications	
Operating voltage	U <sub>B</sub> 10 ... 30 V DC
No-load supply current	I <sub>0</sub> max. 230 mA at 10 V DC max. 100 mA at 24 V DC
Time delay before availability	t <sub>v</sub> < 250 ms
Linearity	± 2 LSB at 16 Bit, ± 1 LSB at 13 Bit, ± 0,5 LSB at 12 Bit
Output code	binary code
Code course (counting direction)	programmable, cw ascending (clockwise rotation, code course ascending) cw descending (clockwise rotation, code course descending)
Interface	
Interface type	EtherCAT® CoE (CANopen over EtherCAT, according to CiA DS-301 and DS-406 device profile CiA)
Resolution	
Single turn	up to 16 Bit
Multiturn	up to 14 Bit
Overall resolution	up to 30 Bit

## Technical Data

Transfer rate	10 ... 100 MBit/s
<b>Connection</b>	
Terminal compartment	see ordering information
<b>Standard conformity</b>	
Degree of protection	DIN EN 60529, IP66
Climatic testing	DIN EN 60068-2-78 , no moisture condensation
Emitted interference	EN 61000-6-4:2007/A1:2011
Noise immunity	EN 61000-6-2:2005
Shock resistance	DIN EN 60068-2-27, 100 g, 3 ms
Vibration resistance	DIN EN 60068-2-6, 10 g, 10 ... 2000 Hz
<b>Approvals and certificates</b>	
IECEx approval	
Equipment protection level Gb	IECEx ITS 15.0061X
ATEX approval	
Equipment protection level Gb	ITS 15 ATEX 18372X
<b>Ambient conditions</b>	
Operating temperature	-40 ... 70 °C (-40 ... 158 °F)
Storage temperature	-40 ... 85 °C (-40 ... 185 °F)
<b>Mechanical specifications</b>	
Material	
Combination 1	housing: anodized aluminum flange: anodized aluminum shaft: Stainless steel 1.4404 / AISI 316L
Combination 2 (Inox)	housing: Stainless steel 1.4404 / AISI 316L flange: Stainless steel 1.4404 / AISI 316L shaft: Stainless steel 1.4404 / AISI 316L
Mass	approx. 2600 g (combination 1) approx. 3900 g (combination 2)
Rotational speed	max. 3000 min <sup>-1</sup>
Moment of inertia	180 gcm <sup>2</sup>
Starting torque	≤ 4 Ncm
Shaft load	
Axial	60 N
Radial	80 N
<b>General information</b>	
Use in the hazardous area	see instruction manuals



The use of highly sophisticated microelectronics requires a consistently implemented anti-interference and wiring concept. This becomes all the more important the more compact the constructions are and the higher the demands are on the performance of modern machines.

The following installation instructions and proposals apply for "normal industrial environments". There is no ideal solution for all interfering environments.

When the following measures are applied, the encoder should be in perfect working order:

- Termination of the serial line with a 120  $\Omega$  resistor (between Receive/Transmit and Receive/Transmit) at the beginning and end of the serial line (e. g. the control and the last encoder).
- The wiring of the encoder should be laid at a large distance to energy lines which could cause interferences.
- Cable cross-section of the screen at least 4 mm<sup>2</sup>.
- Cable cross-section at least 0,14 mm<sup>2</sup>.
- The wiring of the screen and 0 V should be arranged radially, if and when possible.
- Do not kink or jam the cables.
- Adhere to the minimum bending radius as given in the data sheet and avoid tensile as well as shearing load.

### Operating instructions

Every encoder manufactured by Pepperl+Fuchs leaves the factory in a perfect condition. In order to ensure this quality as well as a faultless operation, the following specifications have to be taken into consideration:

- Avoid any impact on the housing and in particular on the encoder shaft as well as the axial and radial overload of the encoder shaft.
- The accuracy and service life of the encoder is guaranteed only, if a suitable coupling is used.
- The operating voltage for the encoder and the follow-up device (e. g. control) has to be switched on and off simultaneously.
- Any wiring work has to be carried out with the system in a dead condition.
- The maximum operating voltages must not be exceeded. The devices have to be operated at extra-low safety voltage.

### Notes on connecting the electric screening

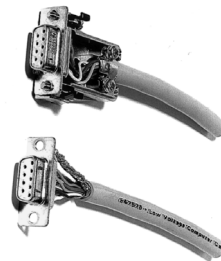
The immunity to interference of a plant depends on the correct screening. In this field installation faults occur frequently. Often the screen is applied to one side only, and is then soldered to the earthing terminal with a wire, which is a valid procedure in LF engineering. However, in case of EMC the rules of HF engineering apply.

One basic goal in HF engineering is to pass the HF energy to earth at an impedance as low as possible as otherwise energy would discharge into the cable. A low impedance is achieved by a large-surface connection to metal surfaces.

The following instructions have to be observed:

- Apply the screen on both sides to a "common earth" in a large surface, if there is no risk of equipotential currents.
- The screen has to be passed behind the insulation and has to be clamped on a large surface below the tension relief.
- In case of cable connections to screw-type terminals, the tension relief has to be connected to an earthed surface.
- If plugs are used, metallised plugs only should be fitted (such as sub D plugs with metallised housing). Please observe the direct connection of the tension relief to the housing.

Advantage:	metallised connector, shield
	clamped with the strain relief
	clamp
Disadvantage:	soldering shield on



### Safety instructions

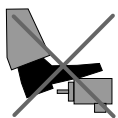
Please observe the national safety and accident prevention regulations as well as the subsequent safety instructions in these operating instructions when working on encoders.

If failures cannot be remedied, the device has to be shut down and has to be secured against accidental operation.

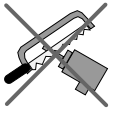
Repairs may be carried out only by the manufacturer. Entry into and modifications of the device are not permissible.

Tighten the clamping ring only, if a shaft has been fitted in the area of the clamping ring (hollow shaft encoders).

Tighten all screws and plug connectors prior to operating the encoder.



Do not stand on the encoder!



Do not remachine the drive shaft!



Avoid impact!



Do not remachine the housing!